

DYNAMIC ALGORITHM CONFIGURATION: Foundation of a New Meta-Algorithmic Framework

André Biedenkapp, H. Furkan Bozkurt, Theresa Eimer,
Frank Hutter, Marius Lindauer

University of Freiburg and Leibnitz University Hannover

ECAI2020

Motivation



Algorithm

Parameter

Image sources given at the end of the presentation



Instances

0 Gold
0 Silver
0 Bronze

Objective

Algorithm Configuration

Motivation



Algorithm



Parameter



Instances

1 Gold
0 Silver
0 Bronze

Objective

Image sources given at the end of the presentation

Motivation



Algorithm

Parameter

Instances

Objective



1 Gold
1 Silver
0 Bronze

Image sources given at the end of the presentation

Motivation



Algorithm



Parameter



Image sources given at the end of the presentation



Instances

1 Gold
0 Silver
0 Bronze

Objective

Motivation



Algorithm



Parameter



1 Gold
1 Silver
0 Bronze

Image sources given at the end of the presentation

Per-Instance Algorithm Configuration

Motivation

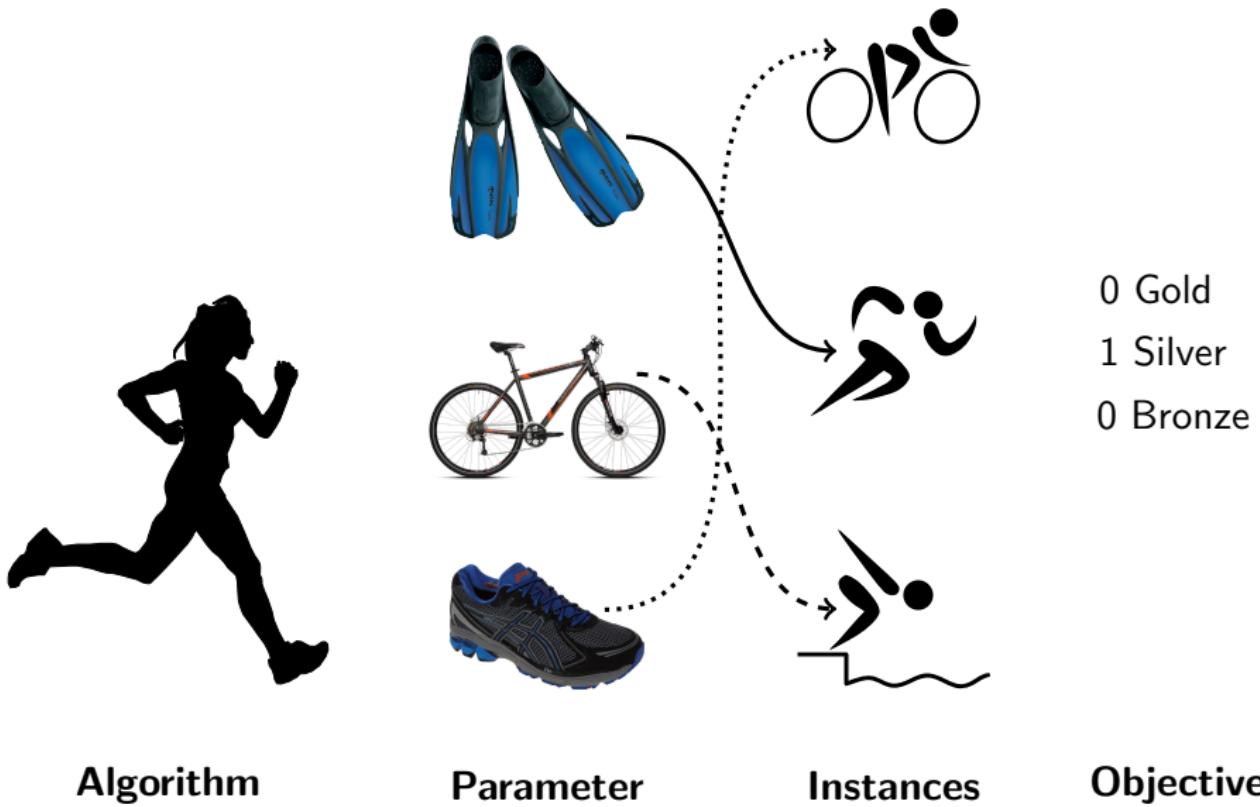


Image sources given at the end of the presentation

Motivation

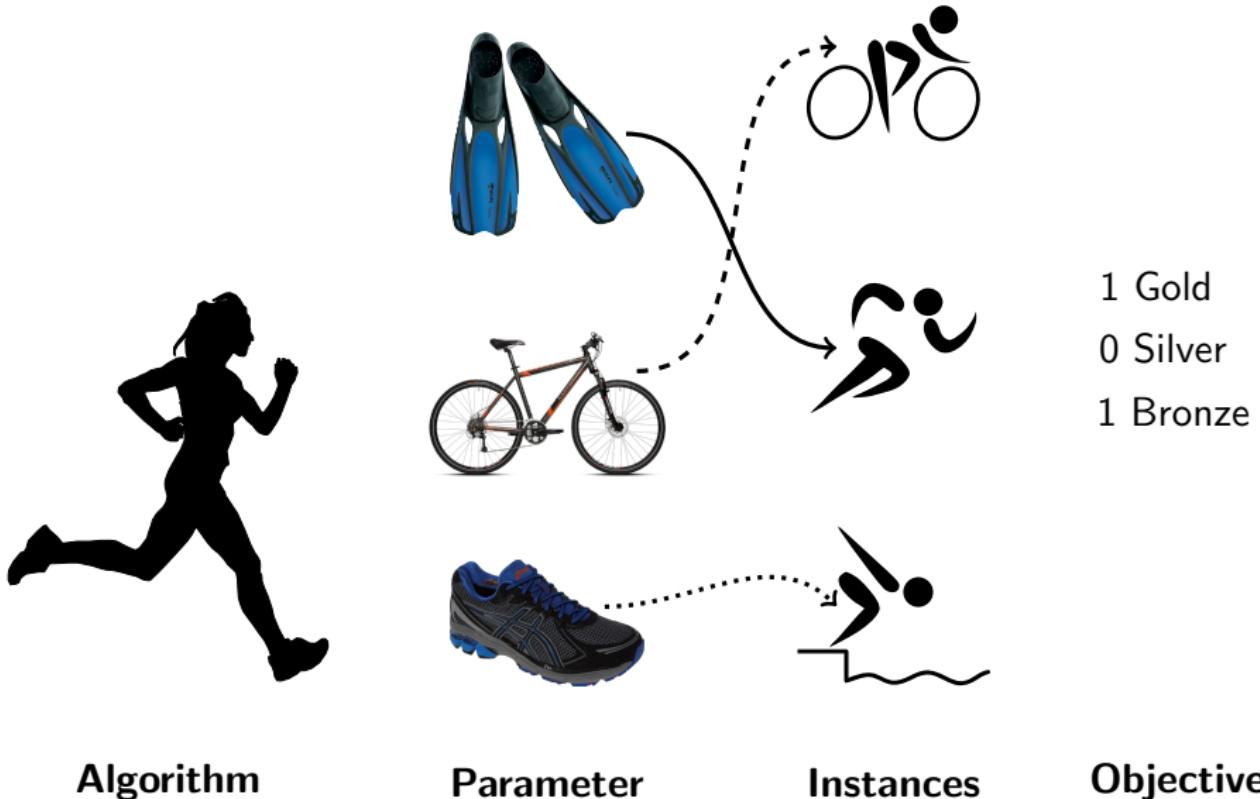


Image sources given at the end of the presentation

Motivation

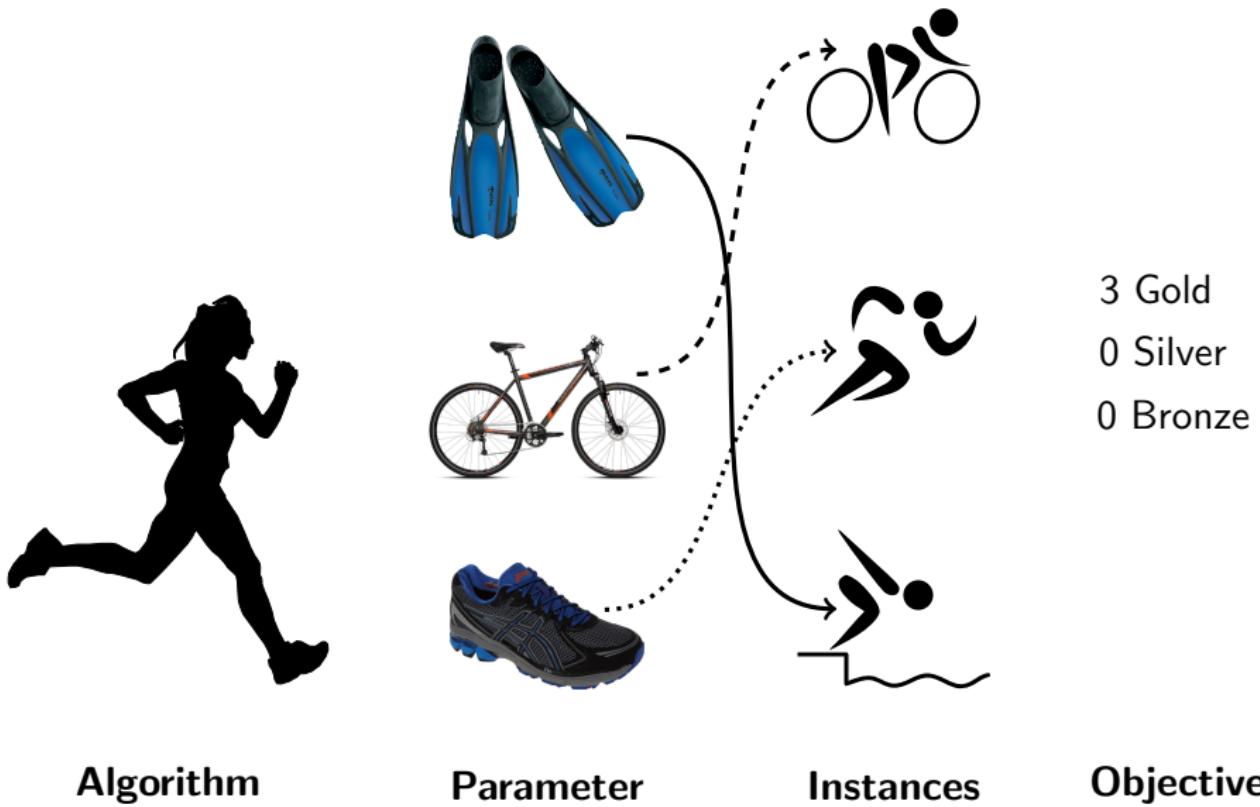


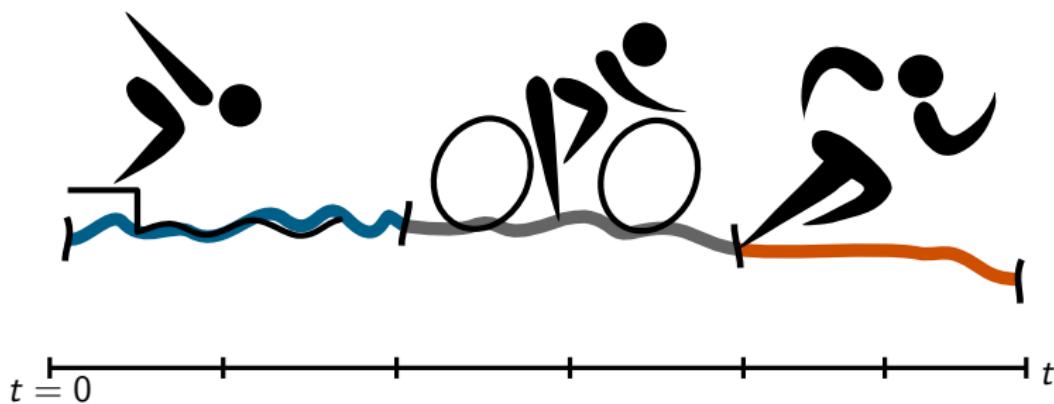
Image sources given at the end of the presentation



How can we solve such problem instances?

Dynamic Algorithm Configuration

Dynamic Algorithm Configuration

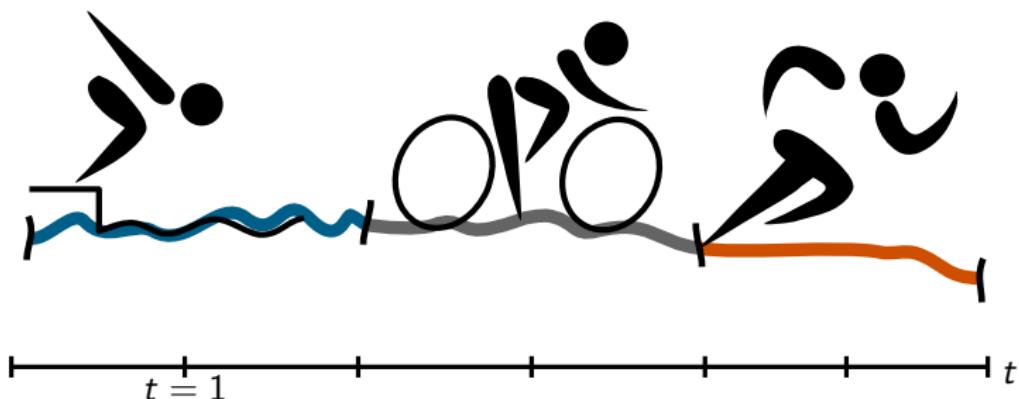


Start from some default:



Image sources given at the end of the presentation

Dynamic Algorithm Configuration



Observe state: Water

Image sources given at the end of the presentation

Dynamic Algorithm Configuration

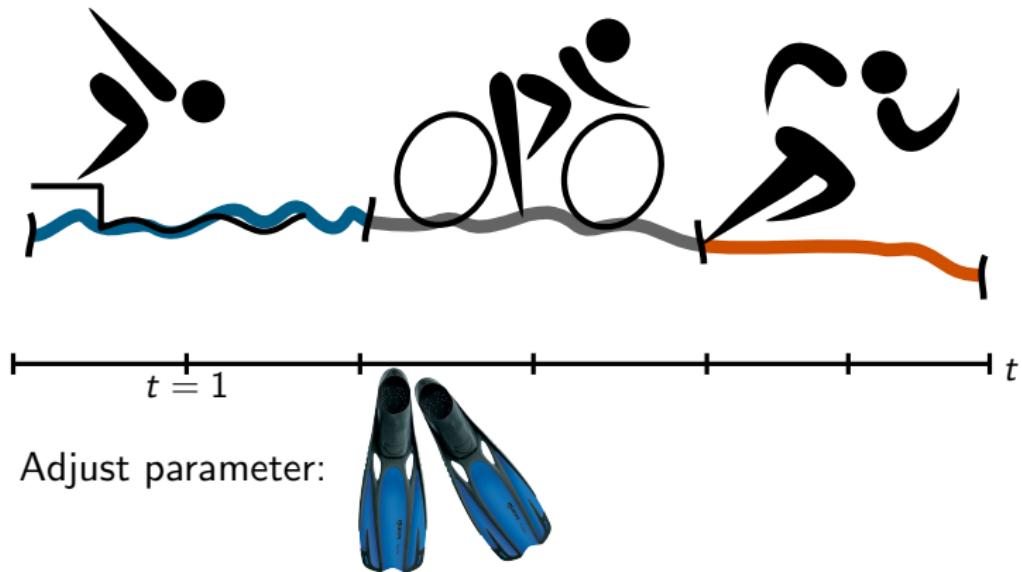
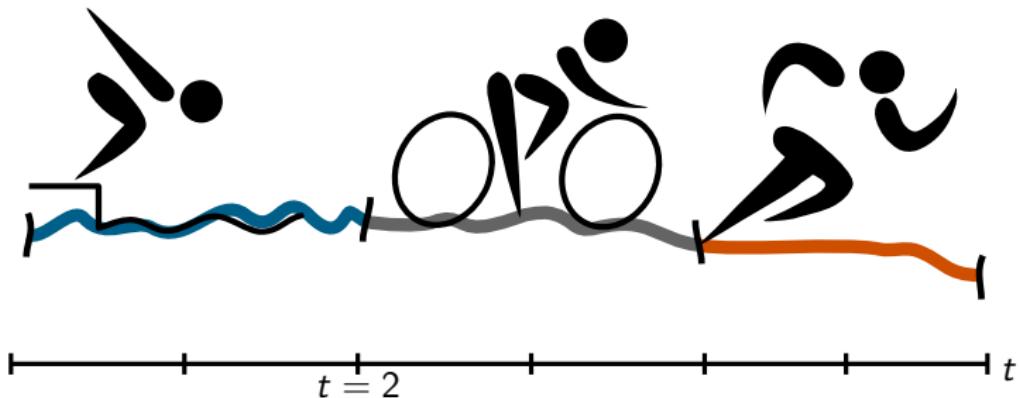


Image sources given at the end of the presentation

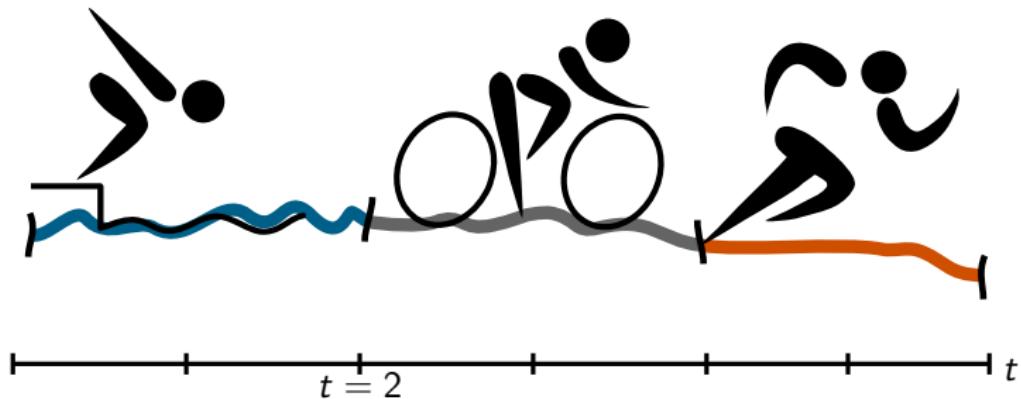
Dynamic Algorithm Configuration



Observe state: Bike Trail

Image sources given at the end of the presentation

Dynamic Algorithm Configuration

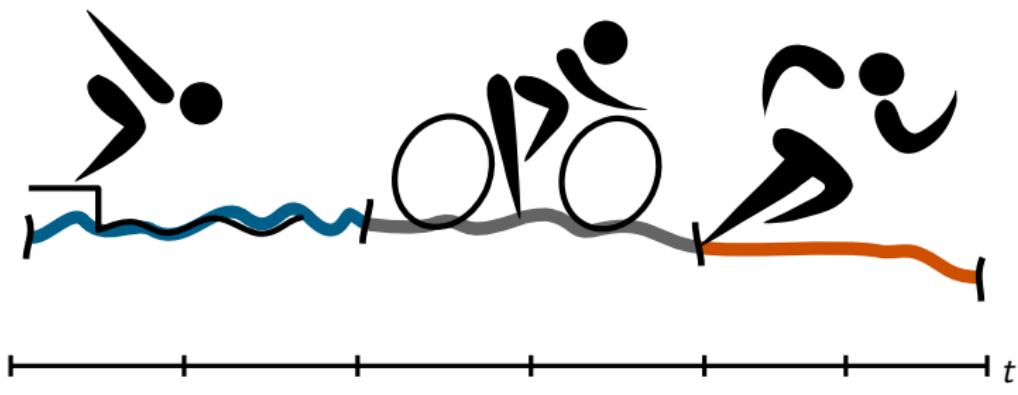


Adjust parameter:



Image sources given at the end of the presentation

Dynamic Algorithm Configuration



...

Image sources given at the end of the presentation

Dynamic Algorithm Configuration

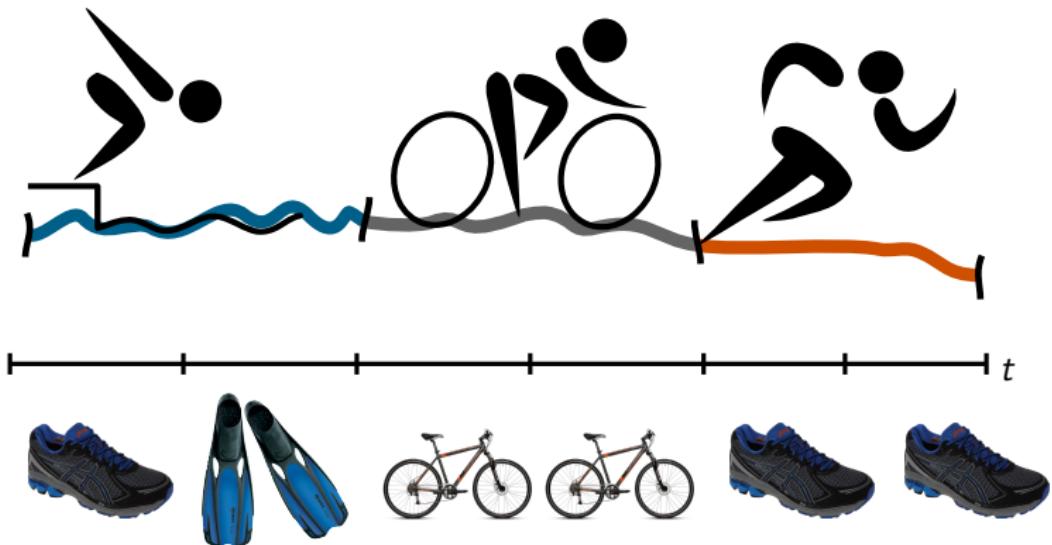


Image sources given at the end of the presentation

Dynamic Configuration as MDP

Formalize optimization as MDP $\mathcal{M} := (\mathcal{S}, \mathcal{A}, \mathcal{T}, \mathcal{R})$

- State Space \mathcal{S}
- Action Space \mathcal{A}
- Transition Function \mathcal{T}
- Reward Function \mathcal{R}

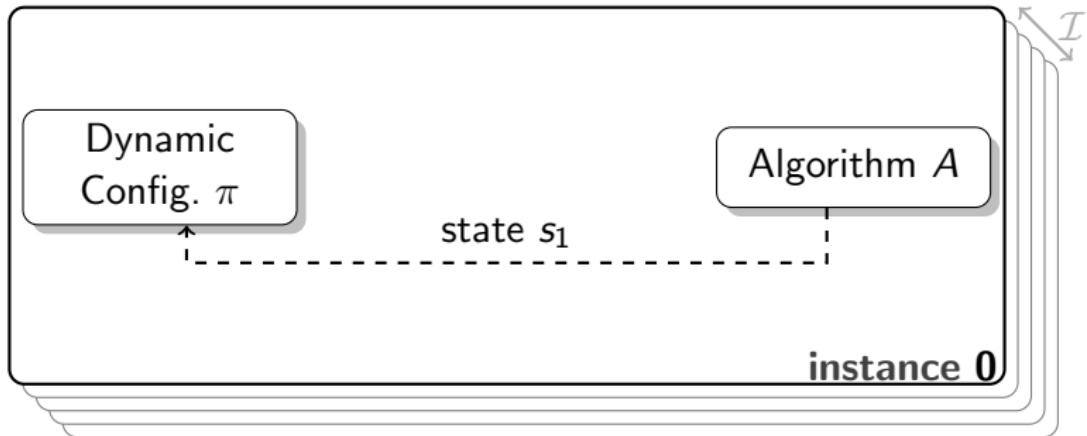


Taking Instances Into Account

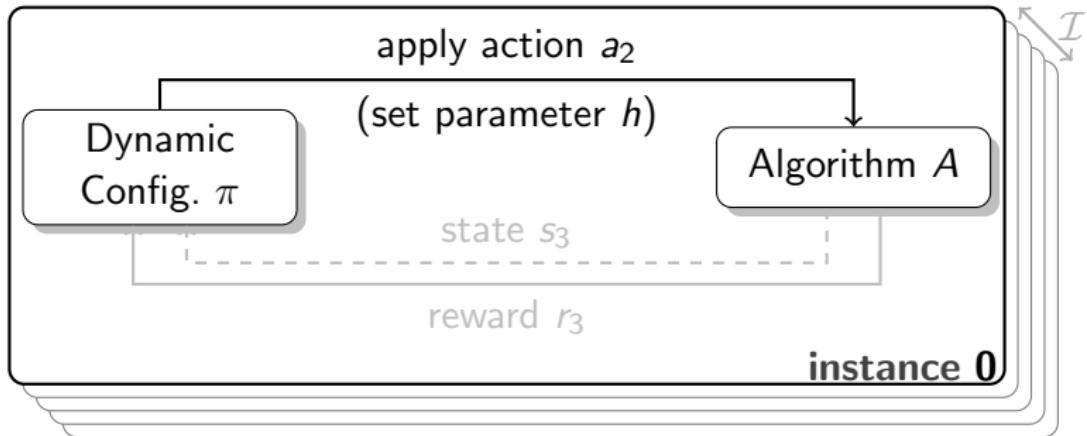
- Instances as context
- Contextual-MDP: $\mathcal{M}_{\mathcal{I}} := \{\mathcal{M}_i\}_{i \sim \mathcal{I}}$
- $\mathcal{M}_i := (\mathcal{S}, \mathcal{A}, \mathcal{T}_i, \mathcal{R}_i)$



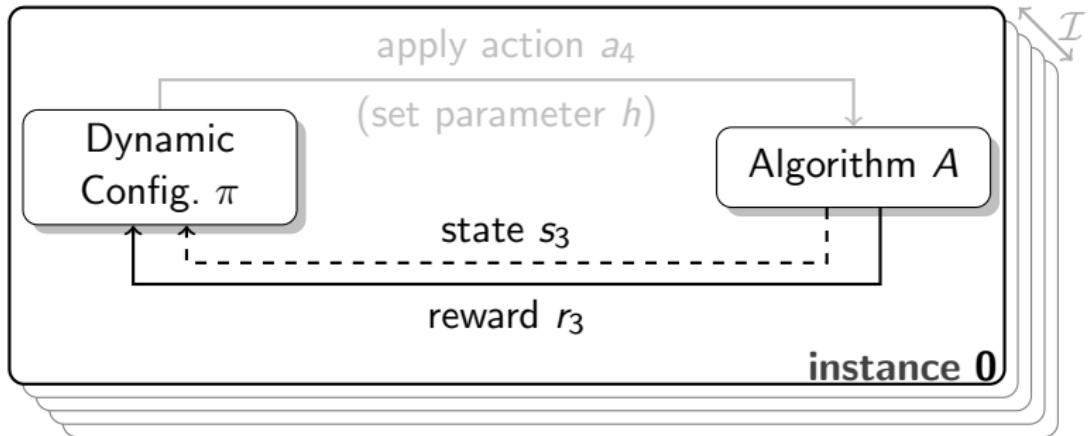
Taking Instances Into Account



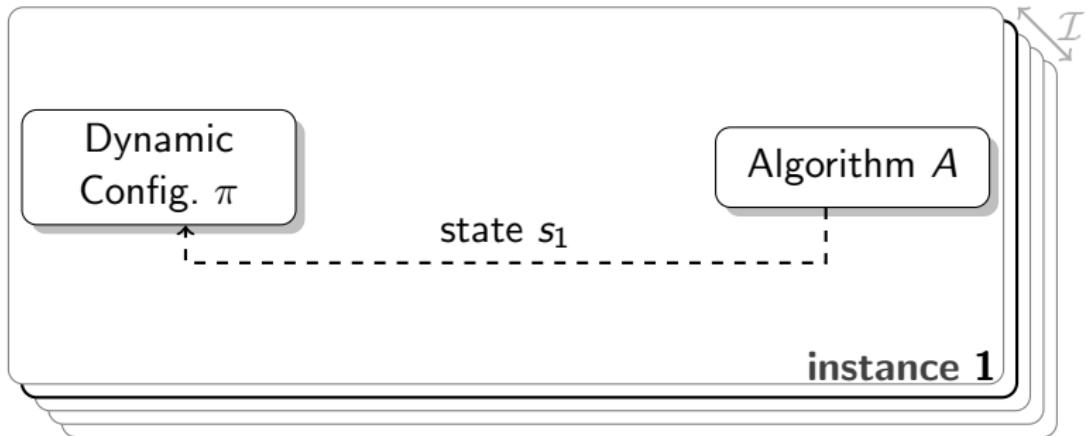
Taking Instances Into Account



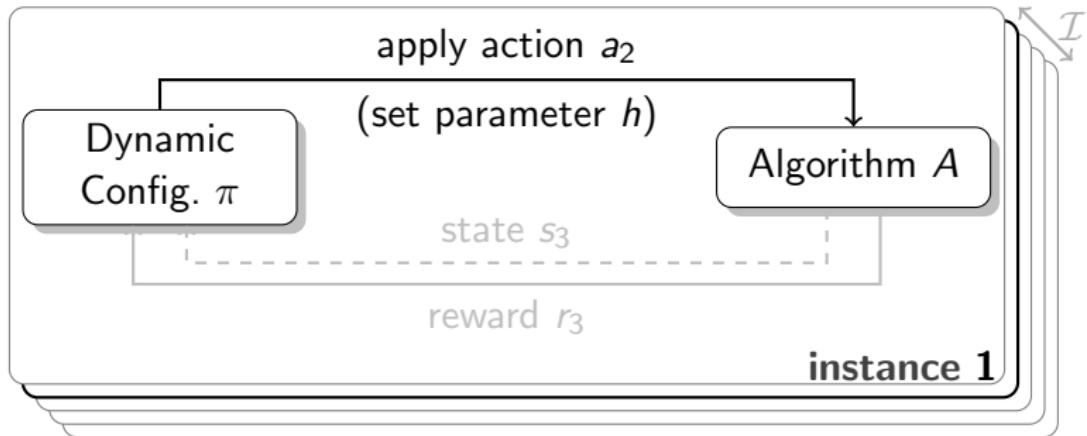
Taking Instances Into Account



Taking Instances Into Account



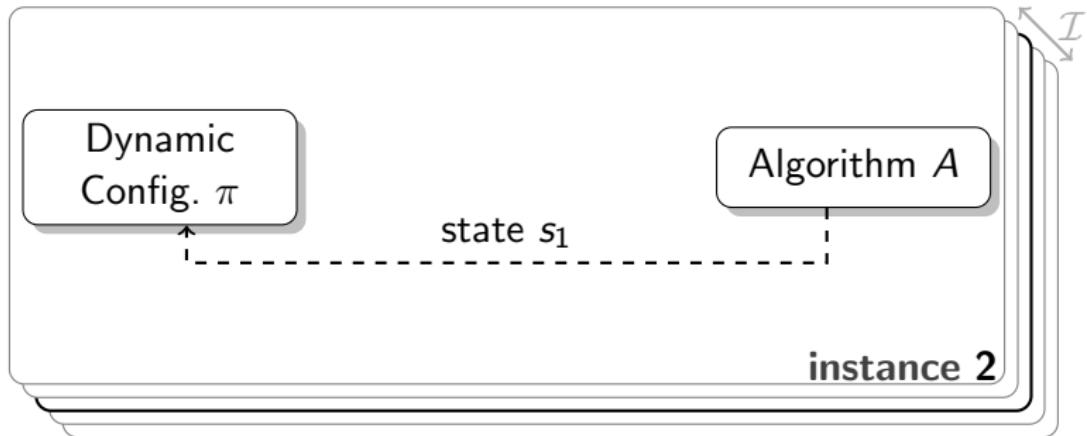
Taking Instances Into Account



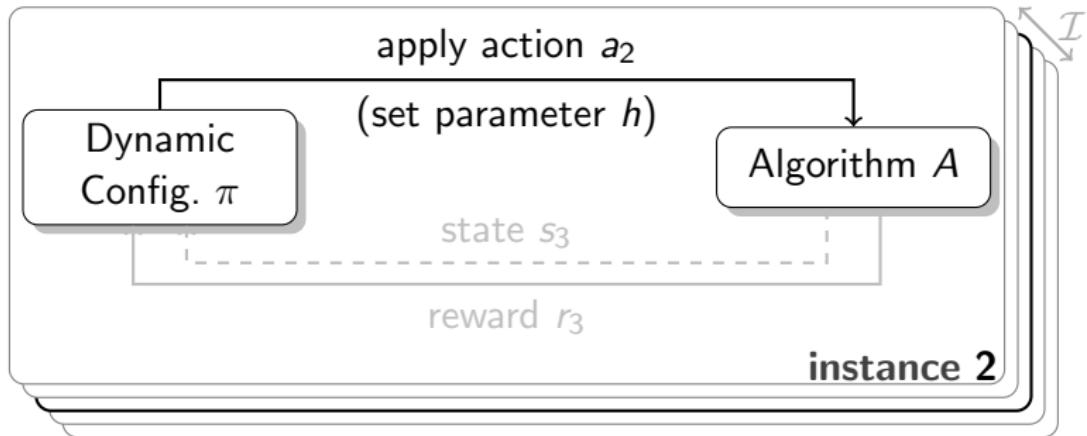
Taking Instances Into Account



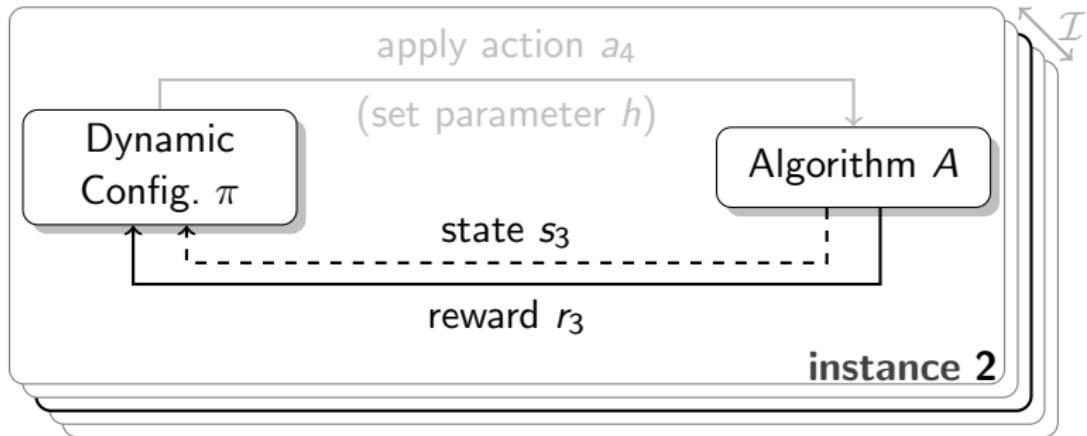
Taking Instances Into Account



Taking Instances Into Account



Taking Instances Into Account



Experimental Design

We designed benchmarks to gain insights into the following settings:

- Effect of Short Effective Sequence Length
- Stochasticity of Reward Signal
- Homogeneity of Instances
- Generalization
- Scaling with the Number of Parameters
- Effect of Self-Paced Learning



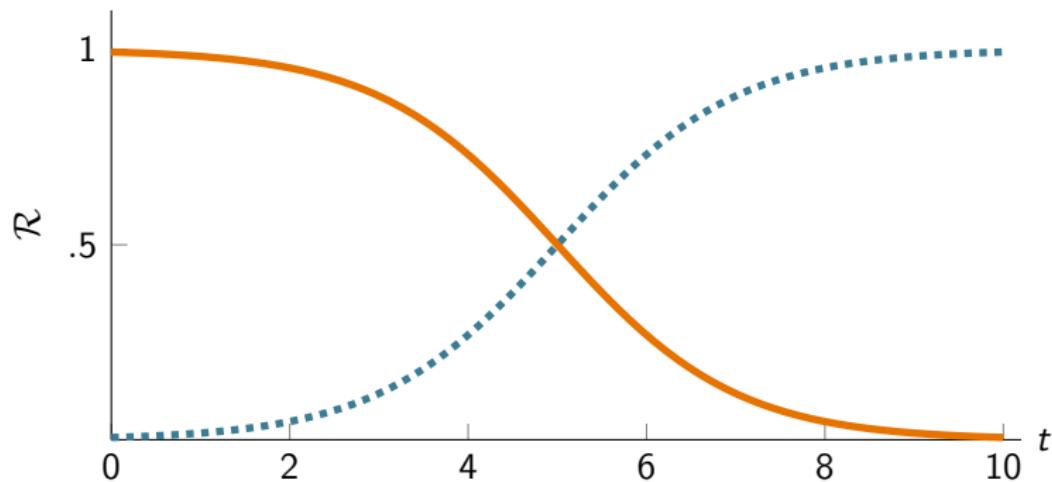
Experimental Design

We designed benchmarks to gain insights into the following settings:

- Effect of Short Effective Sequence Length
- Stochasticity of Reward Signal
- Homogeneity of Instances
- Generalization
- Scaling with the Number of Parameters
- Effect of Self-Paced Learning



Experimental Design

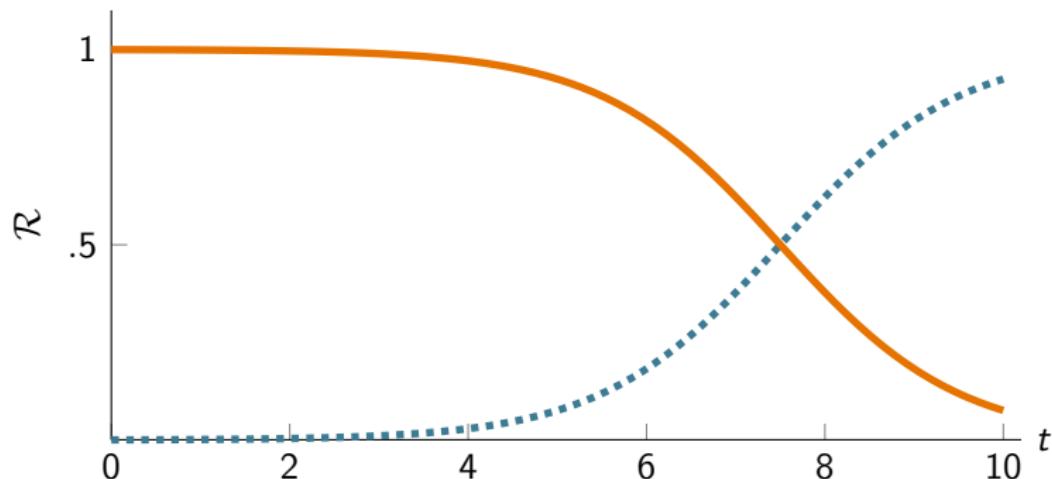


..... reward action 0

— reward action 1



Experimental Design

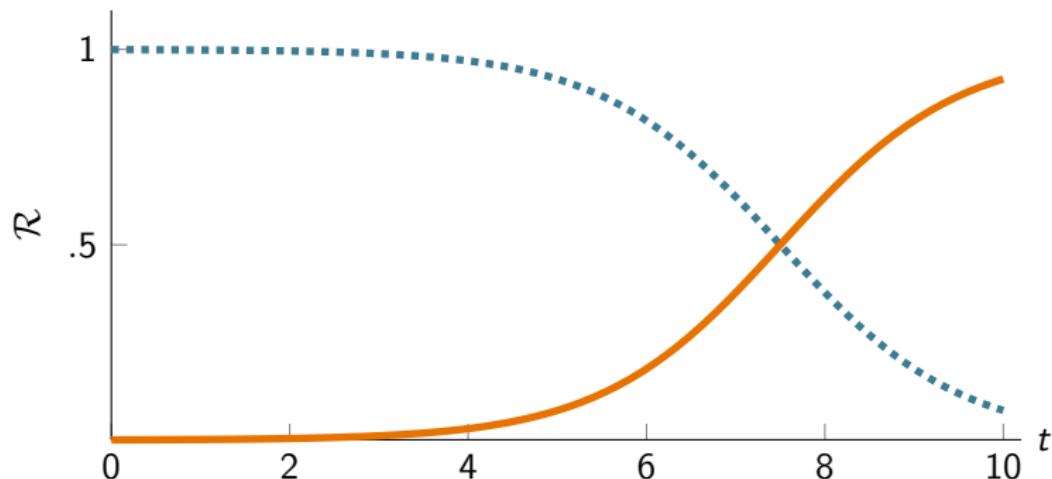


..... reward action 0

— reward action 1



Experimental Design

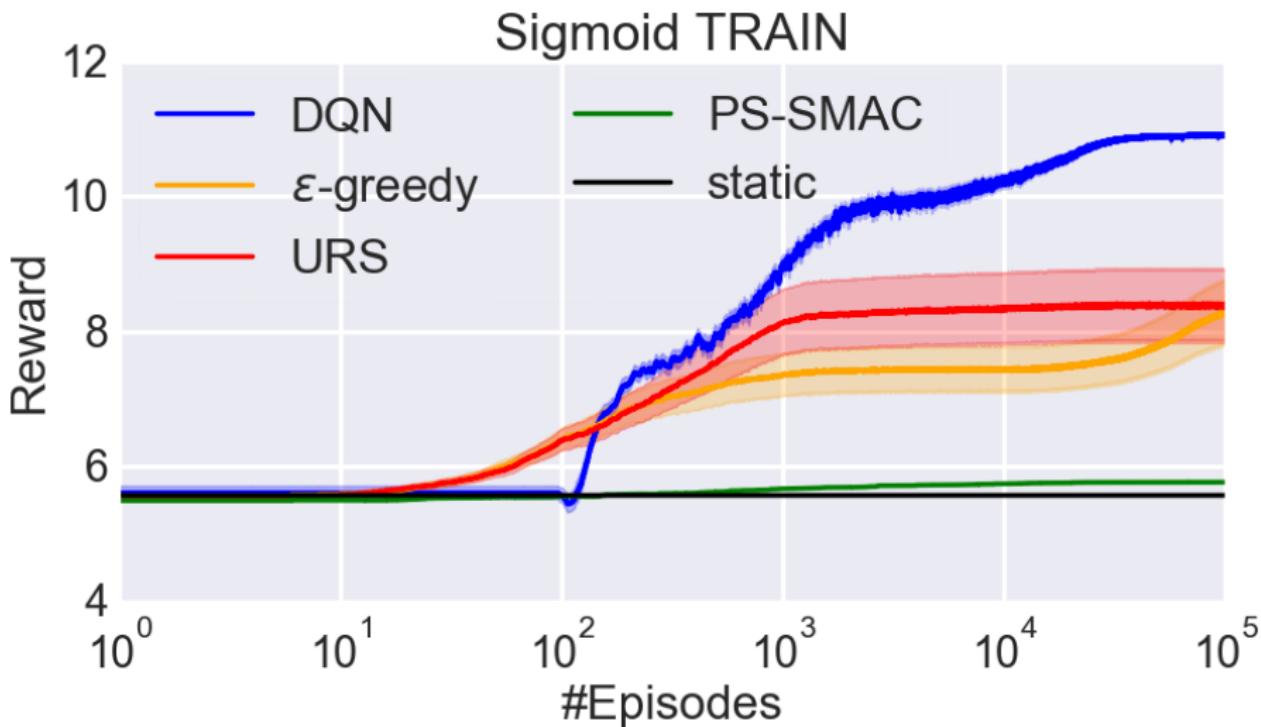


..... reward action 0

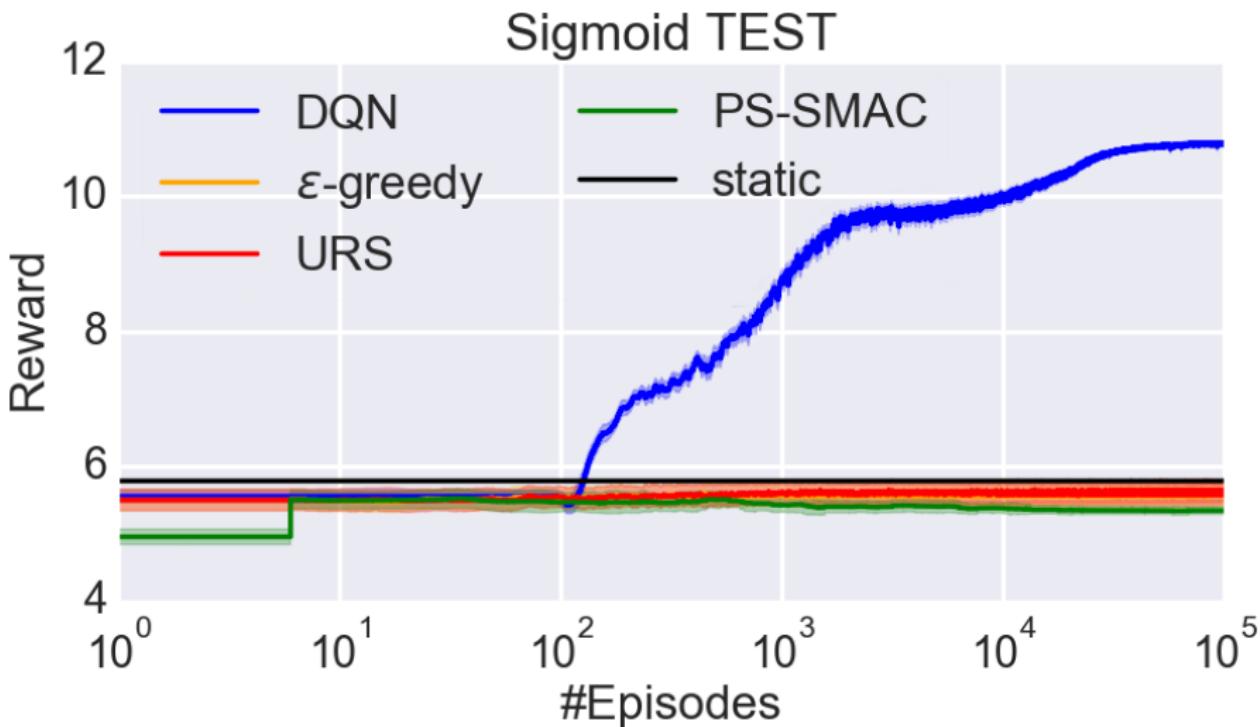
— reward action 1



Sigmoid: Instance sets



Sigmoid: Instance sets



Wrap-up

- We presented a new meta-algorithmic framework
- We demonstrated that the framework is a generalisation of prior frameworks
- Finally we demonstrated the effectiveness of the framework
 - Effect of Short Effective Sequence Length
 - Stochasticity of Reward Signal
 - Homogeneity of Instances
 - Generalization
 - Scaling with the Number of Parameters
 - Effect of Self-Paced Learning



Image Sources

- Female Runner (by [algotruneman](#) under [CC0 1.0](#))
- Running Shoe (under [CC BY-NC 4.0](#))
- Bike (under [CC BY-NC 4.0](#))
- Flippers (under [CC BY-NC 4.0](#))
- Cycling Pictogram
(by [Parutakupiu](#) & [Thadius856](#) under public domain)
- Athletics Pictogram
(by [Parutakupiu](#) & [Thadius856](#) under public domain)
- Swimming Pictogram
(by [Parutakupiu](#) & [Thadius856](#) under public domain)
- The above images were flipped/rotated or scaled and used to depict abstract representations of Algorithm Configuration

